

ST790 — Fall 2022

Imprecise-Probabilistic Foundations of Statistics

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Week 07a

- Compare Dempster & generalized Bayes
- Two general phenomena:
 - dilation
 - contraction
- Paradoxical?
- Perspectives (mine and others)

- We've seen different rules for updating imprecise probs:
 - Dempster's rule
 - Generalized Bayes rule
- There are others, these are just the ones we've discussed
- It's worth asking: *how do they compare?*
- This leads to consideration of
 - dilation
 - contraction
- Presentation is based on Gong & Meng (*Stat Sci* 2021)¹

¹https://ruobingong.github.io/files/GongMeng2021_StatSci.pdf

- Setup:
 - prior is a belief function, has a credal set
 - can apply both Dempster & generalized Bayes updates
- Issues *not* present in precise probability:
 - have to choose a rule
 - can have counter-intuitive/paradoxical results
- If imprecise prob can give counter-intuitive results, why not just stick with precise prob since I know it “works”?
- Two key points:
 - precise prob “works” because of strong assumptions
 - our intuition is based on experiences with how precise prob behaves under unrealistically-ideal circumstances

- Universe \mathbb{X} , finite in the examples here
 - $A \subseteq \mathbb{X}$ is a generic event
 - $\mathcal{B} = \{B_1, B_2, \dots\}$ a partition
- *Generalized Bayes rule:*
 - \mathcal{P} is a closed convex set of probabilities on \mathbb{X}
 - update \mathcal{P} based on B

$$\bar{P}_{\mathcal{B}}(A | B) = \sup_{P \in \mathcal{P}} \frac{P(A \cap B)}{P(B)}, \quad B \in \mathcal{B}$$

- *Dempster's rule:*
 - \mathcal{P} is the credal set corresponding to prior belief \underline{P}
 - update \underline{P} based on B

$$\bar{P}_{\mathcal{D}}(A | B) = \frac{\sup_{P \in \mathcal{P}} P(A \cap B)}{\sup_{P \in \mathcal{P}} P(B)}, \quad B \in \mathcal{B}$$

Example: boxer, wrestler, and coin³

- Two stage experiment:
 - fair coin is flipped, $X = 1$ (heads)
 - boxer and wrestler fight, $Y = 1$ (boxer wins)
- What's "P($Y = 1 \mid X = Y$)"?
- Challenges:
 - don't know marginal distribution of Y
 - don't know the dependence between X and Y
- We could make *assumptions*² and compute the answer
- Imprecise probability allows us to avoid assumptions, but not without creating different challenges

²*Manski's Law of Decreasing Credibility*: The credibility of inference decreases with the strength of the assumptions maintained

³Originally from Gelman (*Amer Stat* 2006)

- $\mathbb{X} = \{0, 1\} \times \{0, 1\}$, head-tail & win-loss pairs
- Incomplete/partial prior info about coin:
 - encode as a belief function
 - two focal elements, $A_0 = \{0\} \times \{0, 1\}$ and $A_1 = \{1\} \times \{0, 1\}$
 - $m(A_0) = m(A_1) = 0.5$
- “Prior ignorance” concerning the fight:

$$\underline{P}(Y = y) = 0 \quad \text{and} \quad \bar{P}(Y = y) = 1, \quad y \in \{0, 1\}$$

- Let's see what happens when we update for “ $X = Y$ ” ...

- Two interesting observations...⁴
- Inference about the boxer:
 - Dempster's rule *contracts*
 - $\underline{P}_{\mathcal{D}}(Y = 1 | X = Y) = \overline{P}_{\mathcal{D}}(Y = 1 | X = Y) = 0.5$
 - $\underline{P}_{\mathcal{D}}(Y = 1 | X \neq Y) = \overline{P}_{\mathcal{D}}(Y = 1 | X \neq Y) = 0.5$
 - vacuous prior turns precise
- Inference about the coin:
 - Generalized Bayes rule *dilates*
 - $\underline{P}_{\mathcal{B}}(X = 1 | X = Y) = 0, \overline{P}_{\mathcal{B}}(X = 1 | X = Y) = 1$
 - $\underline{P}_{\mathcal{B}}(X = 1 | X \neq Y) = 0, \overline{P}_{\mathcal{B}}(X = 1 | X \neq Y) = 1$
 - precise prior turns vacuous
- Both rules give counter-intuitive/paradoxical results
- *Dilation* and *contraction* are general phenomena

⁴Similar results in other examples analyzed in Gong & Meng

Theorem — gBayes can't contract.

If \underline{P} and \bar{P} are the lower and upper envelopes of \mathcal{P} , then

$$\inf_{B \in \mathcal{B}} \underline{P}_{\mathfrak{B}}(A | B) \leq \underline{P}(A) \quad \text{and} \quad \sup_{B \in \mathcal{B}} \bar{P}_{\mathfrak{B}}(A | B) \geq \bar{P}(A)$$

- The above conclusion is the property I called “joint coherence” in the previous lecture
- So, no surprise that generalized Bayes has this property
- Proof below
- In particular, gBayes updates avoid sure loss
- *No such guarantee for Dempster's rule*

Proof:⁵ gBayes can't contract.

Assume not, i.e., there exists A such that $\sup_{B \in \mathcal{B}} \bar{P}_{\mathfrak{B}}(A | B) < \bar{P}(A)$.

Credal set is closed so there exists P^A such that $\bar{P}(A) = P^A(A)$. Then:

$$\begin{aligned}\bar{P}(A) &= P^A(A) \\ &= \sum_{B \in \mathcal{B}} P^A(A | B) P^A(B) \\ &\leq \sum_{B \in \mathcal{B}} \underbrace{\bar{P}_{\mathfrak{B}}(A | B)}_{< \bar{P}(A)} P^A(B) \\ &< \bar{P}(A) \quad \leftarrow \text{contradiction!}\end{aligned}$$

□

⁵Also sheds light on the “overfitting” aspect of gBayes

Theorem — gBayes dilates more.

For any A, B

$$\underline{P}_{\mathfrak{B}}(A | B) \leq \underline{P}_{\mathfrak{D}}(A | B) \leq \overline{P}_{\mathfrak{D}}(A | B) \leq \overline{P}_{\mathfrak{B}}(A | B)$$

In other words, if $\mathcal{C}(\mathfrak{B})$ and $\mathcal{C}(\mathfrak{D})$ are the credal sets of conditional probs based on the two rules, then $\mathcal{C}(\mathfrak{D}) \subseteq \mathcal{C}(\mathfrak{B})$

- *Proof:* $\overline{P}_{\mathfrak{D}}(A | B) = \frac{\sup P(A \cap B)}{\sup P(B)} \leq \sup \frac{P(A \cap B)}{P(B)} = \overline{P}_{\mathfrak{B}}(A | B)$
- Avoiding incoherence requires more conservatism
- “more conservatism” = more imprecision = larger credal set
- Conservatism is fine, even good, but not too much

Theorem — gBayes can't sharpen prior ignorance.

Let A be s.t. $\underline{P}(A) = 0$ and $\overline{P}(A) = 1$. If B has $\underline{P}(B) > 0$, then

$$\underline{P}_{\mathfrak{B}}(A | B) = 0 \quad \text{and} \quad \overline{P}_{\mathfrak{B}}(A | B) = 1$$

- *Proof:* Quick sketch...
 - $\overline{P}(A) = 1 \implies \underline{P}(A^c) = 0 \implies \underline{P}(A^c \cap B) = 0$ for all B
 - if $\underline{P}(B) > 0$, then $\exists P \in \mathcal{C}(\underline{P})$ with $P(A^c | B) = 0$
 - then $\underline{P}_{\mathfrak{B}}(A^c | B) = 0$, hence $\overline{P}_{\mathfrak{B}}(A | B) = 1$
- This kind of makes sense, ignorance is strong
- But hard to believe that we can't learn from observations
- Suggests gBayes might be “too conservative”

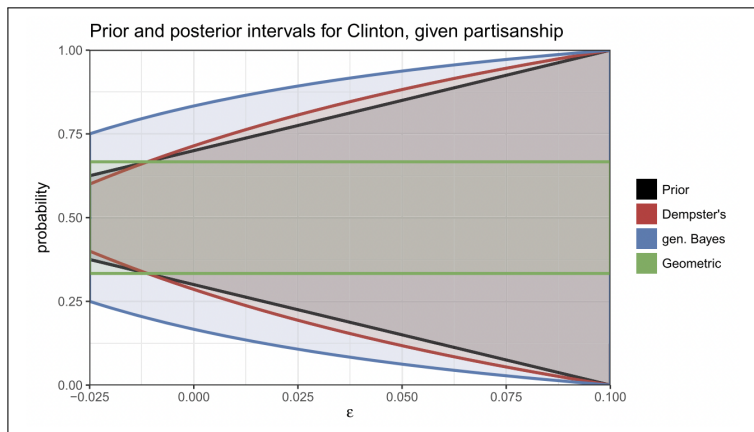
Election example

- Hypothetical *Trump vs. Clinton* election example
- Pre-election poll asks the following questions:
 - Q1 Do you intend to vote for Clinton or Trump?
 - Q2 Do you identify as Democrat or Republican?
- $\mathbb{X} = \{C, T\} \times \{\text{Dem}, \text{Rep}\}$
- Allow for non-response, i.e., set-valued responses
- Hypothetical data interpreted as a belief function
- Parameter ε controls “coarseness”

Q1	C	T	C	T	C	T	—	—	—
Q2	D	D	R	R	—	—	D	R	—
m					$0.1 - \varepsilon$				$0.2 + 8\varepsilon$

Election example, cont.

Plot shows $\underline{P}_*(C | Q2)$ and $\bar{P}_*(C | Q2)$ as a function of ε



- Gong & Meng: “the situation in the world of imprecise probability is more confusing and clearer at the same time”
 - it's right for our models to acknowledge what we don't know
 - imprecise prob gives us the flexibility to do so
 - but do we know how to operate the machine?
- Discussants from the IP community⁶⁷ argue that things are better understood than Gong & Meng suggest
- Roughly, Walley's theory of lower previsions settles it all
- ...except potential dilation

⁶Greg Wheeler and Thomas Augustin & Georg Schollmeyer

⁷Shafer's comments have a different focus, but are very insightful

- My take:
 - in stat/ML, data y is used to learn about θ
 - inference based on map $(y, \dots) \mapsto (\underline{\Pi}_y, \overline{\Pi}_y)$
- Bayes, fiducial, Dempster, gBayes are examples
- *What properties do we want the map to satisfy?*
 - coherence
 - ...
 - **validity**
 - **efficiency**
- Latter two are related to **reliability**, important because now scientific inference is outsourced (e.g., R packages)
- If existing conditioning/updating rules fall short in terms of reliability, then let's come up with something new

- Today is the last lecture about imprecise probability
- Transitioning into “applications”
- Next time: some specifics in *statistical inference*
 - Dempster’s approach
 - generalized Bayes (Walley and others)
 -
 - the “something new” I mentioned above