

ST790 — Fall 2022

Imprecise-Probabilistic Foundations of Statistics

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Week 09a

- Generalized Bayes
- Properties — good & not-so-good
- Walley's formulation for vacuous priors
- IM efficiency considerations

- Recall:

- uncertain $(Y, \Theta) \in \mathbb{Y} \times \mathbb{T}$, imprecise prob $\bar{P}_{Y, \Theta}$
- data $Y = y$ is observed, goal is inference on Θ
- an *inferential model* (IM) is a mapping $(y, \dots) \mapsto (\underline{\Pi}_y, \bar{\Pi}_y)$, output is an imprecise prob on \mathbb{T}
- an IM is *valid* (wrt $\bar{P}_{Y, \Theta}$) if

$$\bar{P}_{Y, \Theta} \{ \bar{\Pi}_Y(A) \leq \alpha, \Theta \in A \} \leq \alpha, \quad (\alpha, A) \in [0, 1] \times 2^{\mathbb{T}}$$

- validity \implies “probabilistic reasoning” is simple & reliable
 - important to emphasize the *wrt...* part
- Last time: Dempster’s construction of an IM
 - Has some nice/interesting features, but not valid
 - Need to keep looking for a valid IM

- Fortunately, other constructions are available
- One of those is *generalized Bayes*
- Walley's *Statistical Reasoning with Imprecise Probabilities* is a book about exactly this¹
- Basic idea: Bayes with a bunch of priors simultaneously
- Statistically relevant points to discuss:
 - coherent
 - *valid*
 - tends to be *inefficient*

¹Walley talks about *lower previsions*, I'll talk about lower/upper probs...

- For simplicity, consider $(Y | \Theta = \theta) \sim P_{Y|\theta}$, precise
- Then $\bar{P}_{Y,\Theta}$ is determined by an imprecise prior for Θ
 - a credal set \mathcal{P}_Θ of precise priors, P_Θ
 - an upper envelope \bar{P}_Θ
- Update $\bar{P}_\Theta \rightarrow \bar{P}_{\Theta|Y}$ based on $Y = y$
- Generalized Bayes rule² says to update as

$$\bar{P}_{\Theta|Y}(\cdot) = \sup_{P_\Theta \in \mathcal{P}} \underbrace{P_{\Theta|Y}(\cdot)}_{\text{Bayes w/ prior } P_\Theta}$$

- Roughly: *Bayes rule applied to a set of priors*

²e.g., Chapters 2 & 7 in *Intro to IP*

- Computation??? More on this below...
- Imprecise/partial prior?
 - classically for robustness, e.g., contamination nbhd's
 - modern focus on marginalization and regularization
- Difference between “robust Bayes” and generalized Bayes is mainly in perspective:
 - robust Bayes *wants* to use a single posterior
 - generalized Bayes will use the set of posteriors
- Does the prior matter?
 - In classical problems, effect of prior washes out asymptotically
 - But partial priors for regularization won't — and we don't want them to!
- What about robustness to the likelihood...?

Theorem — generalized Bayes IM is valid.

^aThe generalized Bayes IM, $\bar{\Pi}_Y = \bar{P}_{\Theta|Y}$, is valid wrt $\bar{P}_{Y,\Theta}$, i.e.,

$$\bar{P}_{Y,\Theta}\{\bar{\Pi}_Y(A) \leq \alpha, \Theta \in A\} \leq \alpha, \quad (\alpha, A) \in [0, 1] \times 2^{\mathbb{T}}$$

^aCorollary 3 in arXiv:2203.06703

- Implies generalized Bayes is (coherent and) reliable
- Special case:
 - the ordinary Bayes IM is valid wrt $P_{Y,\Theta}$
 - validity wrt the Bayes model isn't surprising at all
- The wrt... part is important

- Computation?
- It's the sup over priors that makes this challenging
- For finite \mathbb{T} , the sup is over a closed & convex subset of a finite-dim simplex, not impossible
- For other \mathbb{T} , it's an infinite-dim optimization problem :(
- However, depending on the structure of the prior credal set, some analytical results are available...

- Recall the *contamination neighborhood* example:

$$\mathcal{P}_\Theta = \{(1 - \varepsilon)P^* + \varepsilon Q : \text{any prob } Q \text{ on } \mathbb{T}\}$$

- Here, $\varepsilon \in [0, 1]$ and P^* are fixed
- Closed & convex, so we can take this as a prior credal set and apply generalized Bayes to get $(\underline{\Pi}_y, \overline{\Pi}_y)$
- This prior has enough structure to show,³ e.g., that

$$\underline{\Pi}_y(A) = \frac{(1 - \varepsilon) \int_A L_y(\theta) P^*(d\theta)}{(1 - \varepsilon) \int_{\mathbb{T}} L_y(\theta) P^*(d\theta) + \varepsilon \sup_{A^c} L_y}$$

$$\overline{\Pi}_y(A) = \frac{(1 - \varepsilon) \int_A L_y(\theta) P^*(d\theta) + \varepsilon \sup_A L_y}{(1 - \varepsilon) \int_{\mathbb{T}} L_y(\theta) P^*(d\theta) + \varepsilon \sup_A L_y}$$

³Wasserman (*Annals* 1990), Example 5.2

- Key properties of generalized Bayes:
 - coherent
 - valid
- Computation is non-trivial, but can be done when the prior credal set has enough structure
- But recall that generalized Bayes tends to *dilate*
 - in particular, prior vacuous \implies posterior is vacuous
 - take $\varepsilon = 1$ in above example
- A sign of potential *inefficiency*...

- In statistics, generalized Bayes methods typically fall under the umbrella of “robust Bayes”
- Two special cases developed by Peter Walley:
 - *imprecise Dirichlet model* (IDM)
 - a no-name approach for vacuous priors
- The IDM is for multinomial models, a generalization of the conjugate Dirichlet priors
- Lengthy summary of IDM in Ch. 7 of *Intro to IP*
- I'll focus here on Walley's other idea

- Generalized Bayes proper is useless for vacuous priors
- Walley (*JSPI* 2002) proposed an ingenious workaround
- Take the same (ε, P^*) -contamination neighborhood prior
- Let $\underline{\Pi}_y^\varepsilon$ and $\overline{\Pi}_y^\varepsilon$ denote the gBayes IM output above

Theorem (Walley 2002).

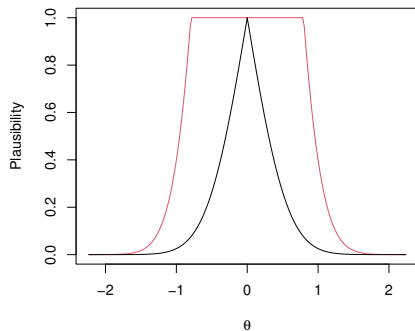
Fix $\bar{\alpha} \in (0, 1)$. Then $y \mapsto (\underline{\Pi}_y^\varepsilon, \overline{\Pi}_y^\varepsilon)$ satisfies:

- coherence
- likelihood principle
- if $\varepsilon \geq (2 - \bar{\alpha})^{-1}$, then it's "valid" (wrt vacuous prior) on a restricted range $\alpha \in [0, \bar{\alpha}]$
- and more...

- Really impressive result!
- (Walley) A Bayesian & frequentist “reconciliation”
 - coherence follows from this being a gBayes solution
 - likelihood principle too (more later)
 - the “and more” says gBayes tests & confidence sets control error rates at levels $\alpha \in [0, \bar{\alpha}]$
- Doesn't get validity exactly, but that's not deal-breaker
 - taking $\bar{\alpha} = 0.5$, say, covers the usual significance levels
 - in that case, take $\varepsilon \geq 2/3$
- Visualization via plausibility contour in Walley's Eq. (3.3)
- Seems to do everything we want...

Examples

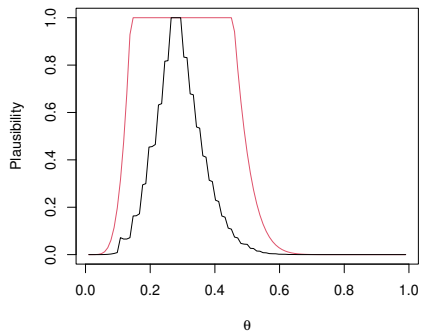
- Normal mean illustration: $(Y | \Theta = \theta) \sim N(\theta, \sigma^2 n^{-1})$
- Contours for two (valid) IM solutions:
 - Walley's with $\varepsilon = \frac{10}{19}$, $P^* = N(0, 3\sigma^2)$
 - mine I'll tell you about soon



$(y = 0, n = 5, \sigma = 1)$

Examples, cont.

- Binomial illustration: $(Y | \Theta = \theta) \sim \text{Bin}(n, \theta)$
- Contours for two (valid) IM solutions:
 - Walley's with $\varepsilon = \frac{10}{19}$, $P^* = \text{Unif}(0, 1)$
 - mine I'll tell you about soon



($y = 7, n = 25$)

- There's a price Walley pays for his “reconciliation”
- Significant⁴ loss of efficiency compared to...
- Walley justifies this as a trade-off for satisfying the likelihood principle, e.g., stopping-rule invariance
- That's fine/nice, but I didn't ask for that
- To me, that's not worth sacrificing (a lot of) efficiency
- Fortunately, we can do better

⁴Even in the *rate*, e.g., $(\log n)^k n^{-1/2}$ compared to usual $n^{-1/2}$

- Towards a valid & efficient IM
 - Possibility measures and *strong validity*
 - Imprecise-probability-to-possibility transform
 - ...
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- Presentation will be based on ideas in a recent paper⁵ and some new stuff I'm working on now

⁵<http://arxiv.org/abs/2203.06703>